



T-ONE SEL-XP TENSION CONTROLLER

Control of closed-loop and combined systems

- ✓ Regulation in torque
- Tension control with load cells or dancing roller
- Can be used with modular brakes
- Can manage wide variations of tension
- Compact design
- Ease of use and calibration

T-one is a tension controller specifically designed for the web tension control in closed-loop and combined systems; extreme ease of use and compactness are the main features of the tension controller. The core of T-one is the P.I.D. algorithm, which has been improved in speed and accuracy.

The interface with 6 buttons and 4 digit is easy to use and allows to smoothly control and set up the desired parameters to obtain the best results.

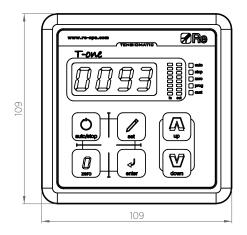
T-one SEL-XP has been specifically designed for those applications that require modular pneumatic brakes for wide variations of diameters and tension.

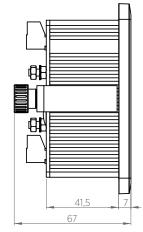
Thanks to the SELEMATIC function, the tension controller can automatically exclude two groups of calipers, sizing the brake dynamically and adapting itself to the required torque to make the regulation more sensitive. The controller, managing an electropneumatic transducer and two solenoids, give the right pressure to the brake.

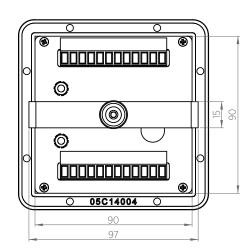


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TECHNICAL DRAWING







APPLICATIONS



Combined regulation in torque with load cells or dancing roller

TECHNICAL DATA

1 setpoint or dancing rolls Digital inputs 24 V Analog output 0÷10 V / 4÷20 mA Analog output 0÷10 V Analog output 0÷10 V Digital relay outputs 24 Vdc /24 Vac Digital relay outputs 24 Vdc /24 Vac Weight Working temperature IP protection class	Power supply	24 Vdc
Digital inputs 24 V 6 remo Analog output 0÷10 V / 4÷20 mA 1 torque mo Analog output 0÷10 V 1 diameter or tension pr or dancing roller pist Digital relay outputs 24 Vdc /24 Vac 2 for alarms or soleno Weight Working temperature IP protection class IP 20 (case) IP 52 (from	Power	8 W max
Analog output 0÷10 V / 4÷20 mA 1 torque mo Analog output 0÷10 V 1 diameter or tension pr or dancing roller pist Digital relay outputs 24 Vdc /24 Vac 2 for alarms or soleno Weight Working temperature IP protection class IP 20 (case) IP 52 (from	Analog inputs 0÷10 V	1 dancing roller 1 diameter 1 setpoint or dancing roller pressure
Analog output 0÷10 V 1 diameter or tension pr or dancing roller pist Digital relay outputs 24 Vdc /24 Vac 2 for alarms or soleno Weight Working temperature IP protection class IP 20 (case) IP 52 (from	Digital inputs 24 V	6 remote controls
or dancing roller pist Digital relay outputs 24 Vdc /24 Vac 2 for alarms or soleno Weight Working temperature IP protection class IP 20 (case) IP 52 (from	Analog output 0÷10 V / 4÷20 mA	1 torque motor control
Weight Working temperature IP protection class IP 20 (case) IP 52 (fro	Analog output 0÷10 V	1 diameter or tension proportional or dancing roller piston control
Working temperature IP protection class IP 20 (case) IP 52 (fro	Digital relay outputs 24 Vdc /24 Vac	2 for alarms or solenoids control
IP protection class IP 20 (case) IP 52 (fro	Weight	400 g
	Working temperature	0÷50°C
Dimensions 109 x 10	IP protection class	IP 20 (case) IP 52 (frontal panel)
*Data are subject to technical change without notice		109 x 109 x 67 mm

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